



# Schedulability analysis of PWM tasks for the UPMSat-2 ADCS.

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#### Motivation

- Schedulability study of the ADCS subsytem implementing a PWM control algorithm
- Study of Ravenscar Profile restrictions

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# **UPMSat-2**



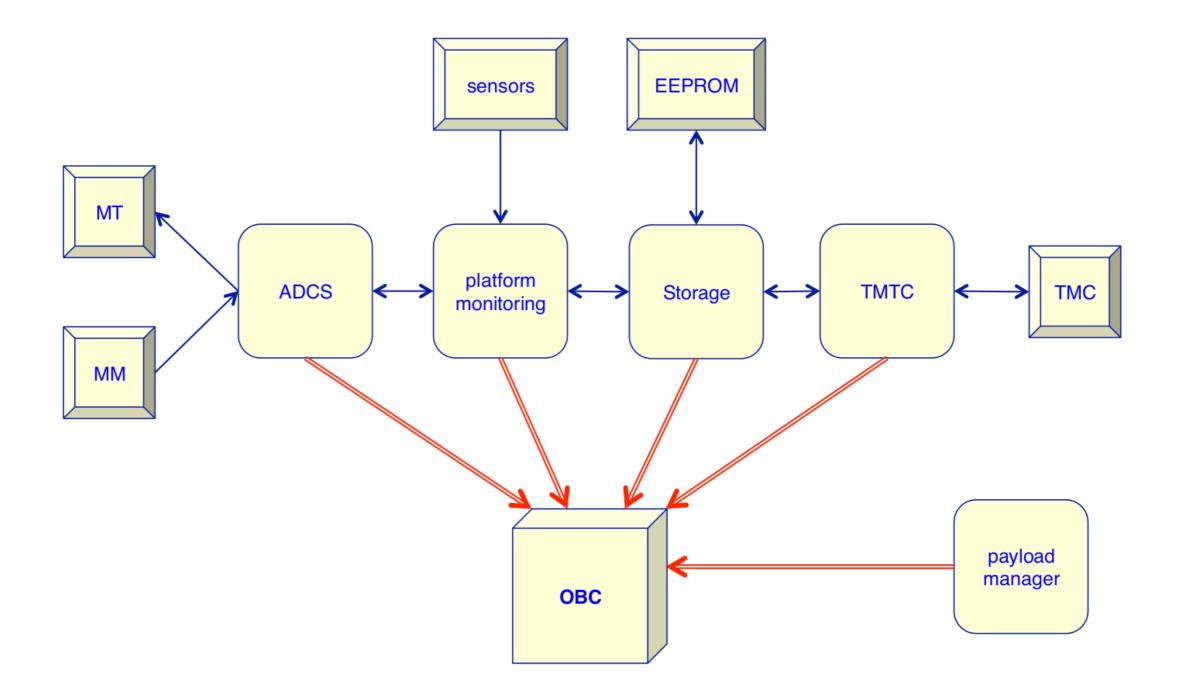
- UPM project
  - Previous experience UPMSat-1
- Developed from scratch
  - Industrial collaboration
- Academic research
  - ADCS, thermal control, ...
  - Real-time software engineering

# **UPMSat-2**

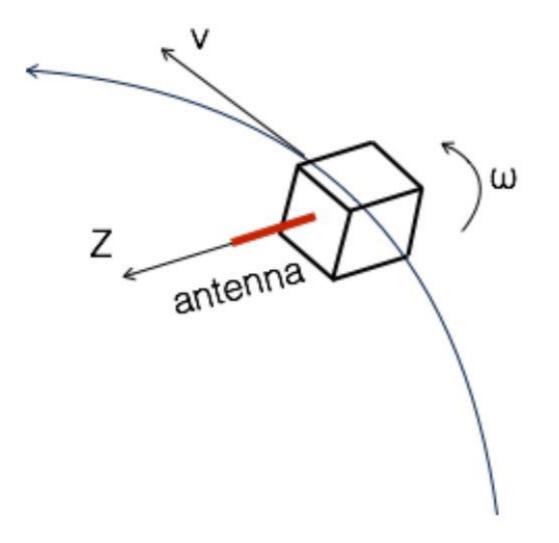
- Experimental microsatellite to be launched in 2016
  - 50 x 50 x 60 cm envelope
  - Sun-synchronous orbit at 600 km altitude
  - Technology demonstrator
  - Experiment payload



#### SW overview

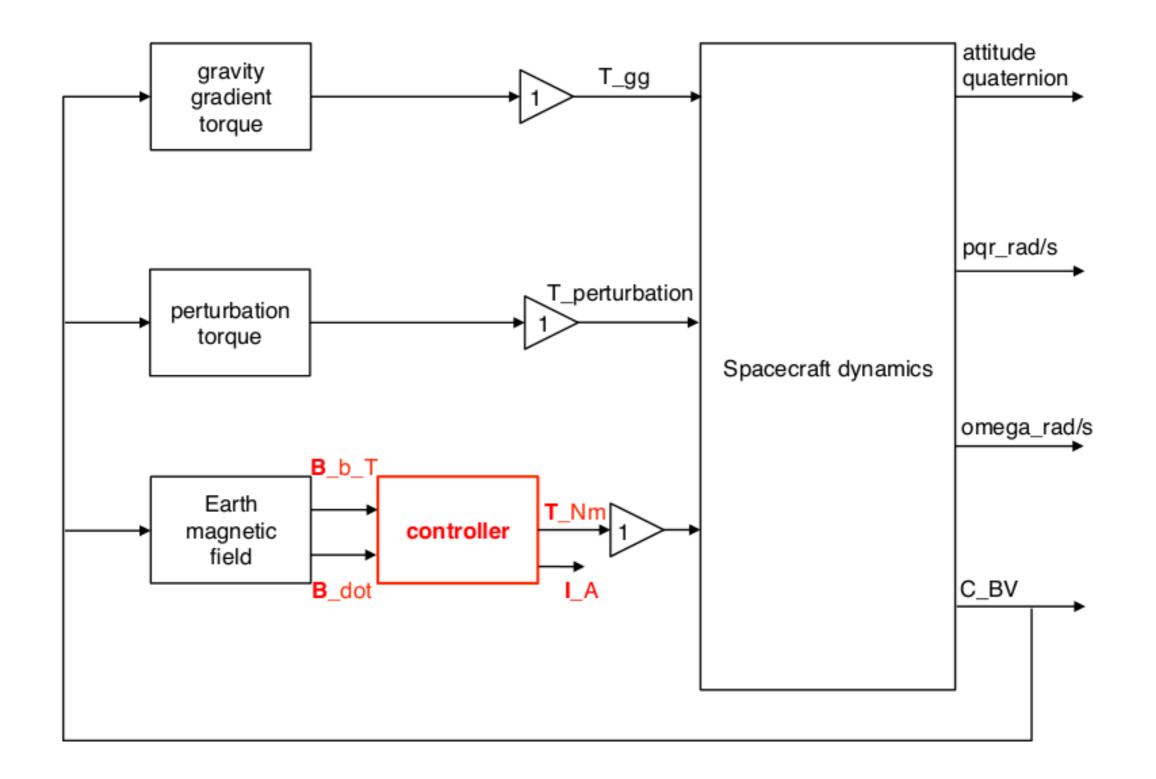


## Attitude Determination and Control System



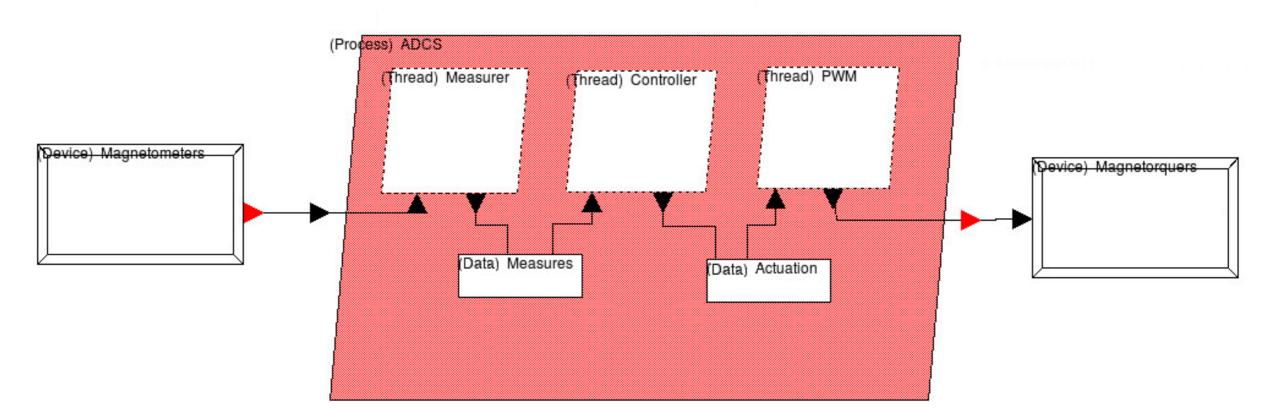
- Active control system
- Constant angular speed
- Based on Earth's magnetic field
- Model-based development

## Simulink ADCS model

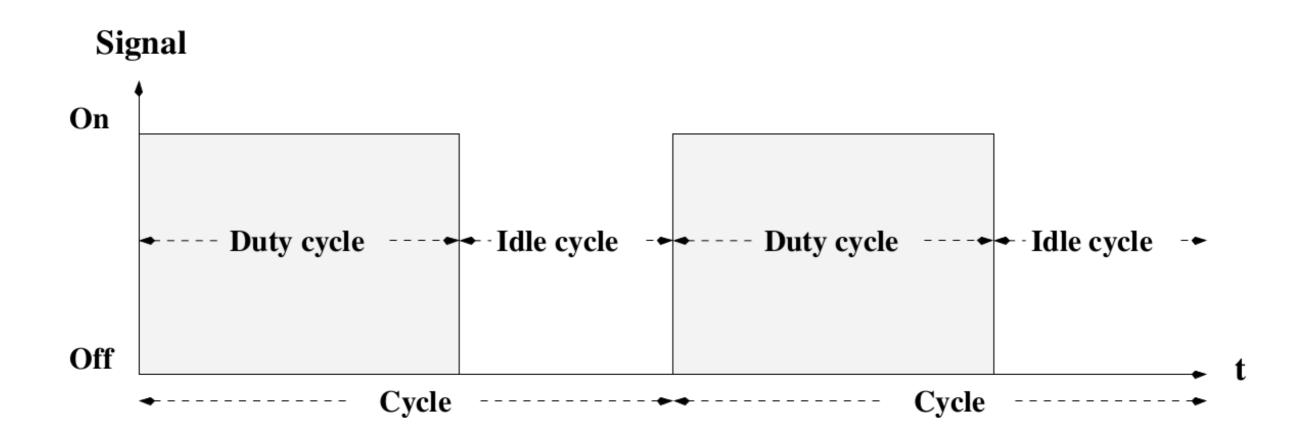


#### ADCS software architecture

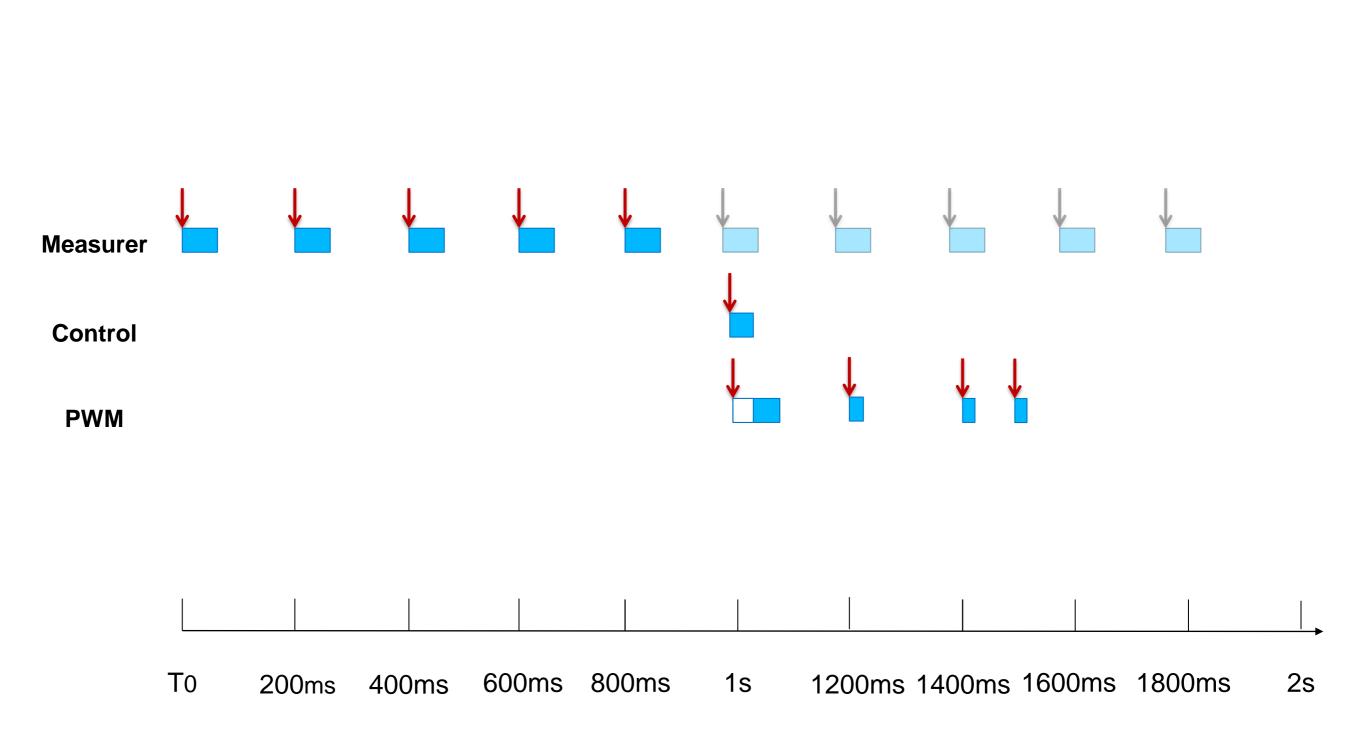
- 2 seconds cycle: 1<sup>st</sup> measurements, 2<sup>nd</sup> actuation
  Magnetometers can't be read while actuating on magnetorquers
- PWM actuation implemented by software

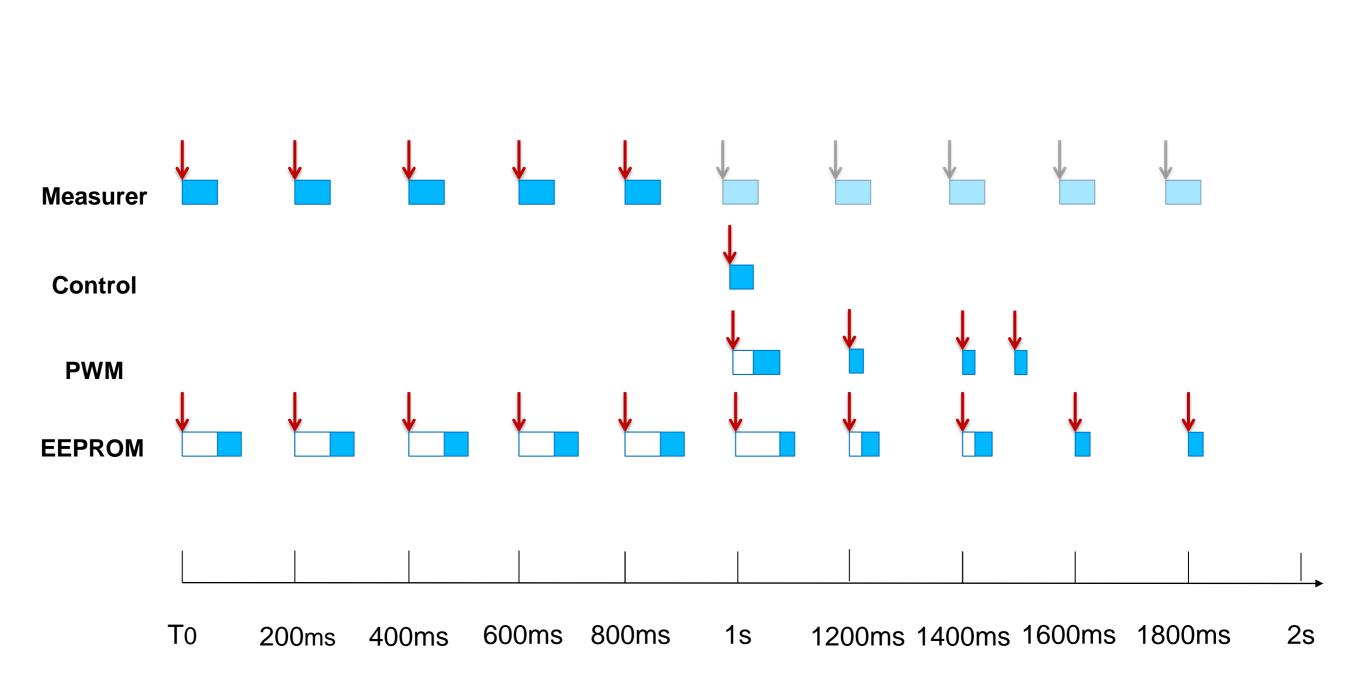


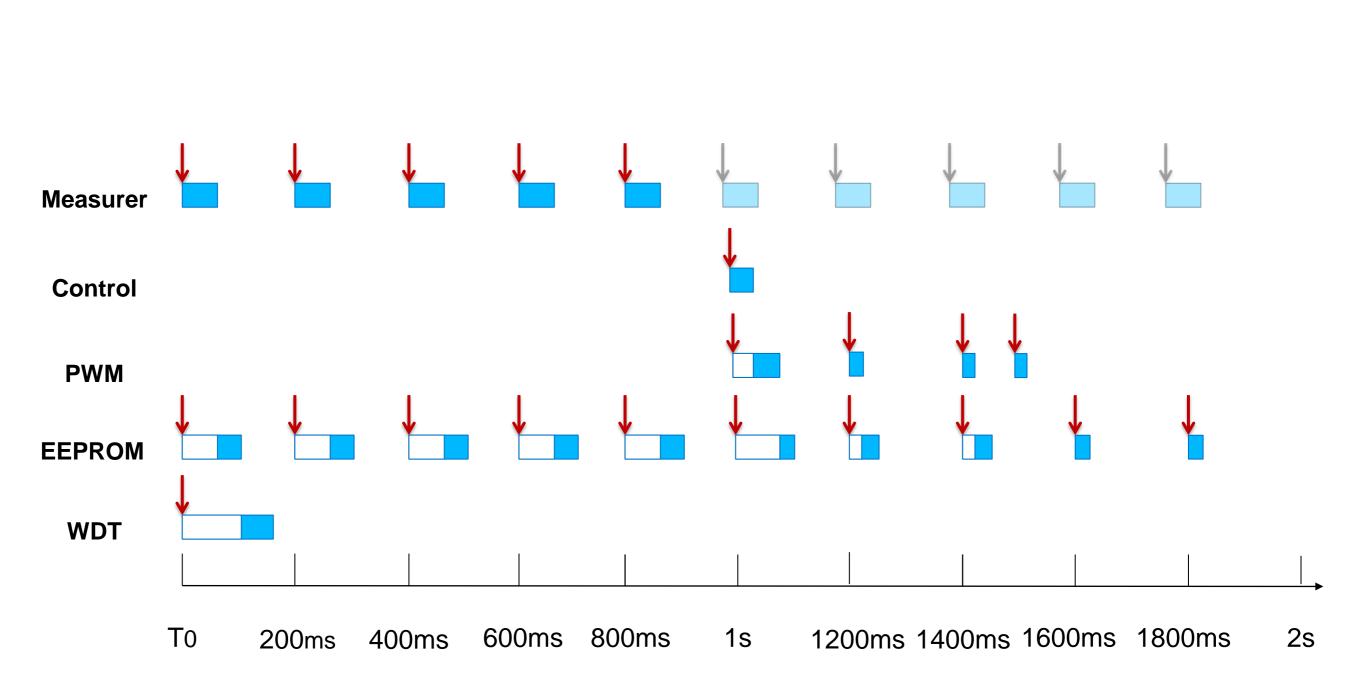
### **Pulse Width Modulation**

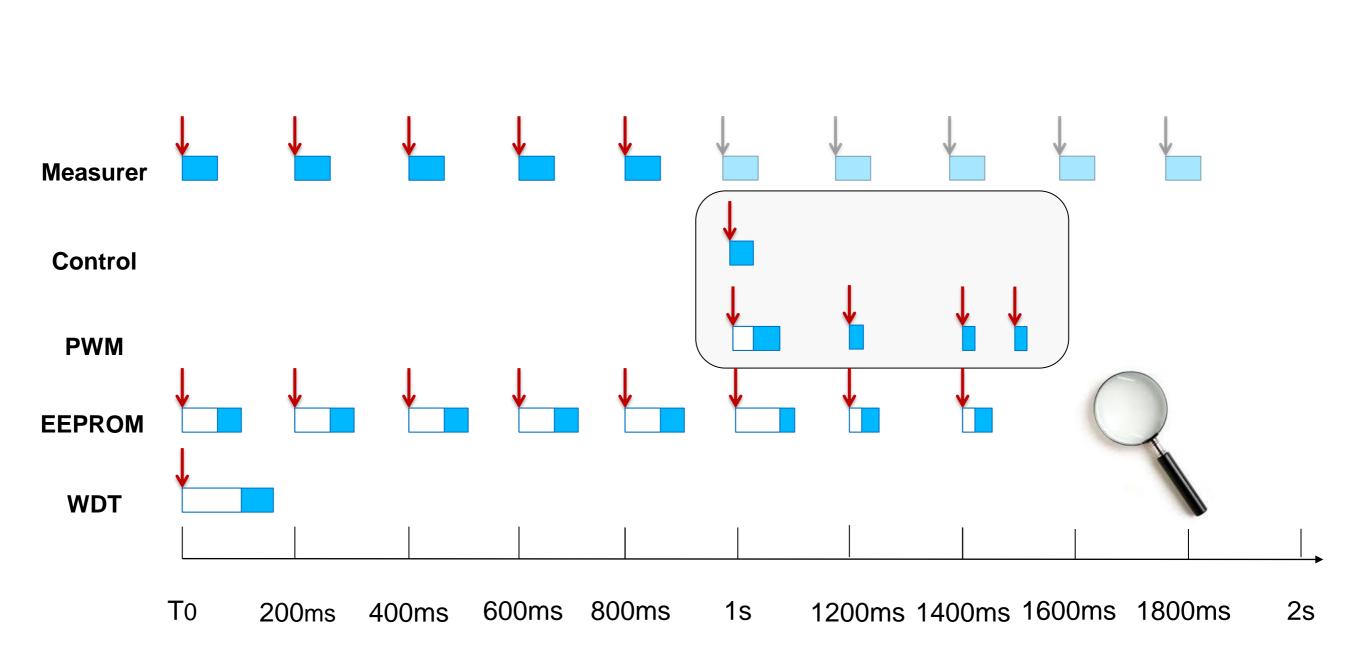


ADCS duty cycles: 0, 200, 300, 400, 500 ms

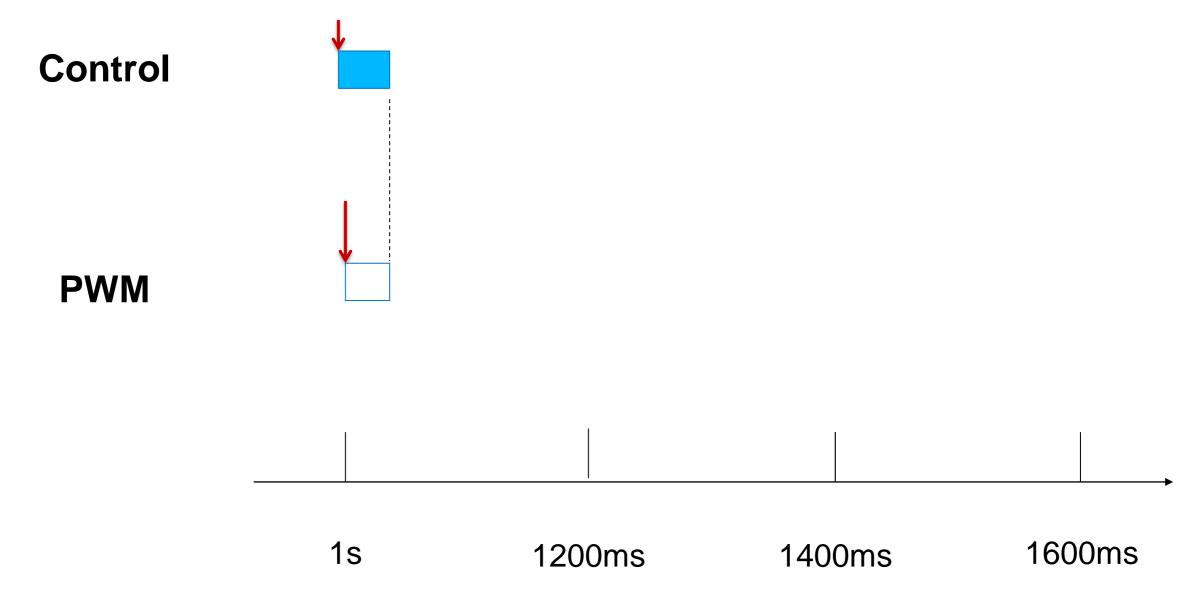






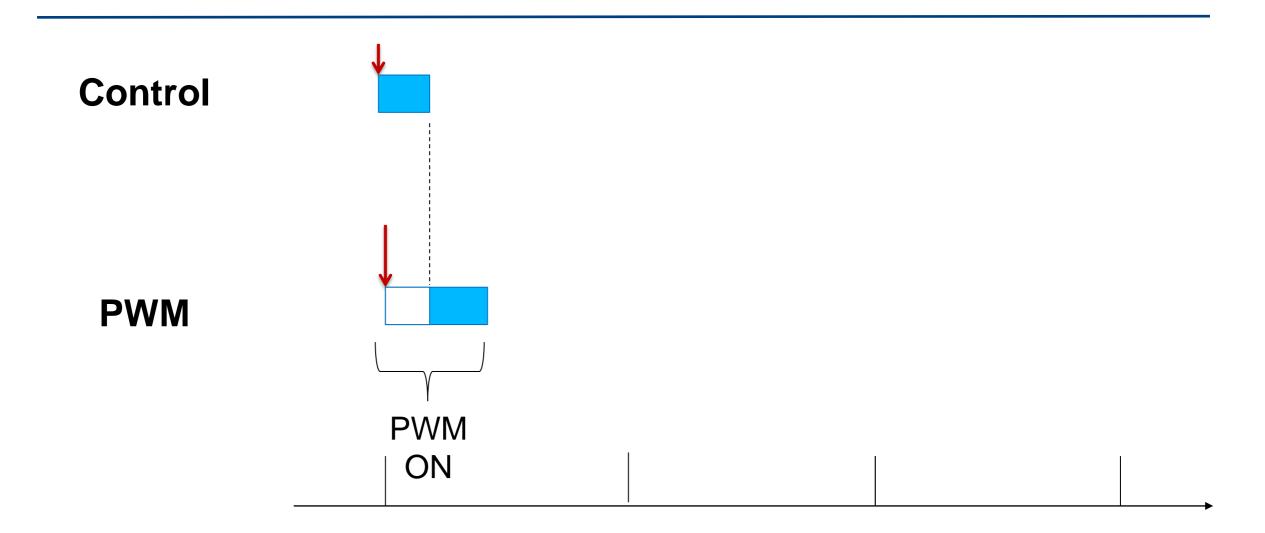


#### **PWM detail**



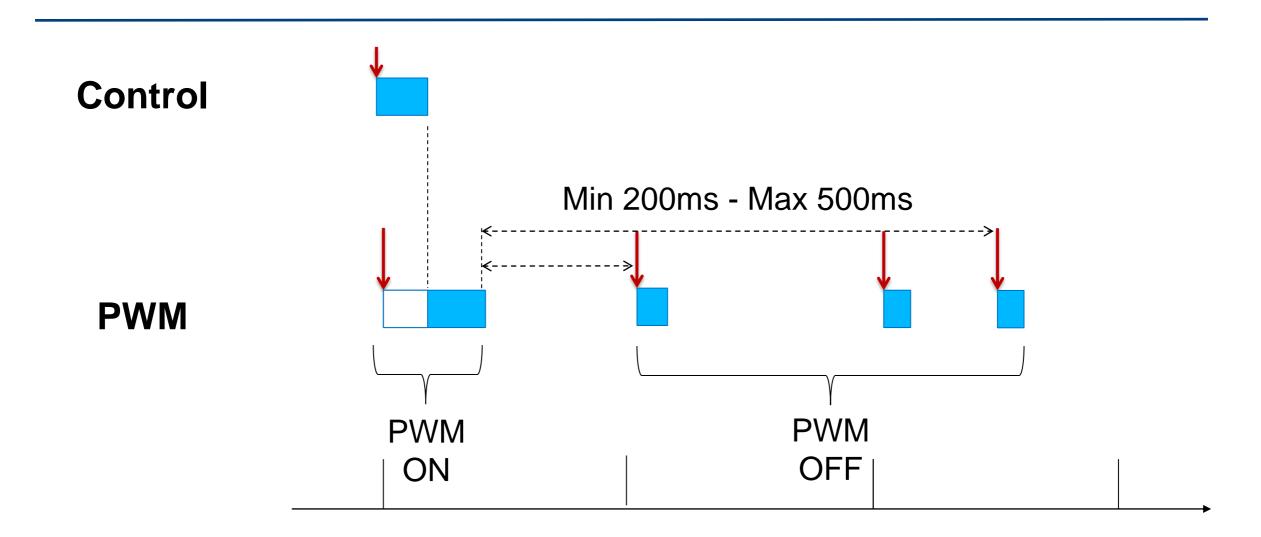
Task	Period	Offset	Release jitter	Deadline	WCET
Control	2 s	$1 \mathrm{s}$	0		4.02  ms
$PWM_{On}$		$1 \mathrm{s}$	$R_{Control}$		$2.41 \mathrm{ms}$
$PWM_{Off}$	2 s	1200  ms	$300 \text{ ms} + \text{R}_{PWM_{On}}$	800  ms	$0.8 \mathrm{ms}$

#### **PWM detail**



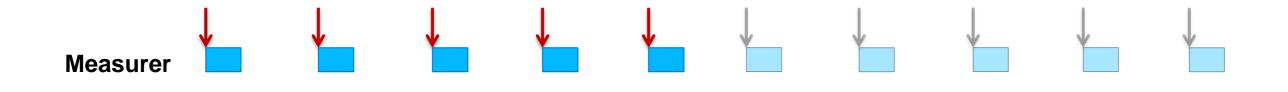
	1s		1200ms 140	0ms	1600ms
Task	Period	Offset	Release jitter	Deadline	WCET
Control	2 s	$1 \mathrm{s}$	0		4.02  ms
$PWM_{On}$	2 s	$1 \mathrm{s}$	$R_{Control}$		$2.41 \mathrm{ms}$
$PWM_{Off}$	2 s	1200  ms	$300 \text{ ms} + \text{R}_{PWM_{Or}}$	800 ms	$0.8 \mathrm{ms}$

## **PWM detail**



	1s		1200ms 14	00ms	1600ms
Task	Period	Offset	Release jitter	Deadline	WCET
Control	2 s	1 s	0		4.02  ms
$PWM_{On}$	2 s	$1 \mathrm{s}$	$R_{Control}$		$2.41 \mathrm{ms}$
$[PWM_{Off}]$	$2 \mathrm{s}$	1200  ms	$300 \text{ ms} + \text{R}_{PWM_C}$	$n 800 \mathrm{ms}$	$0.8 \mathrm{ms}$

Measurer task is very pessimistic on the later second

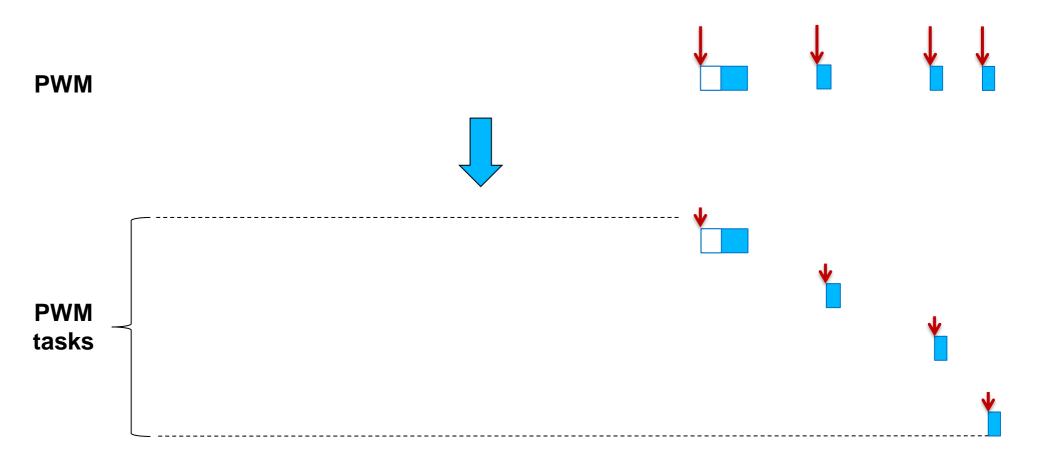


 Measurer task is very pessimistic on the later second It can be modeled as 5 tasks Measure Measurer tasks

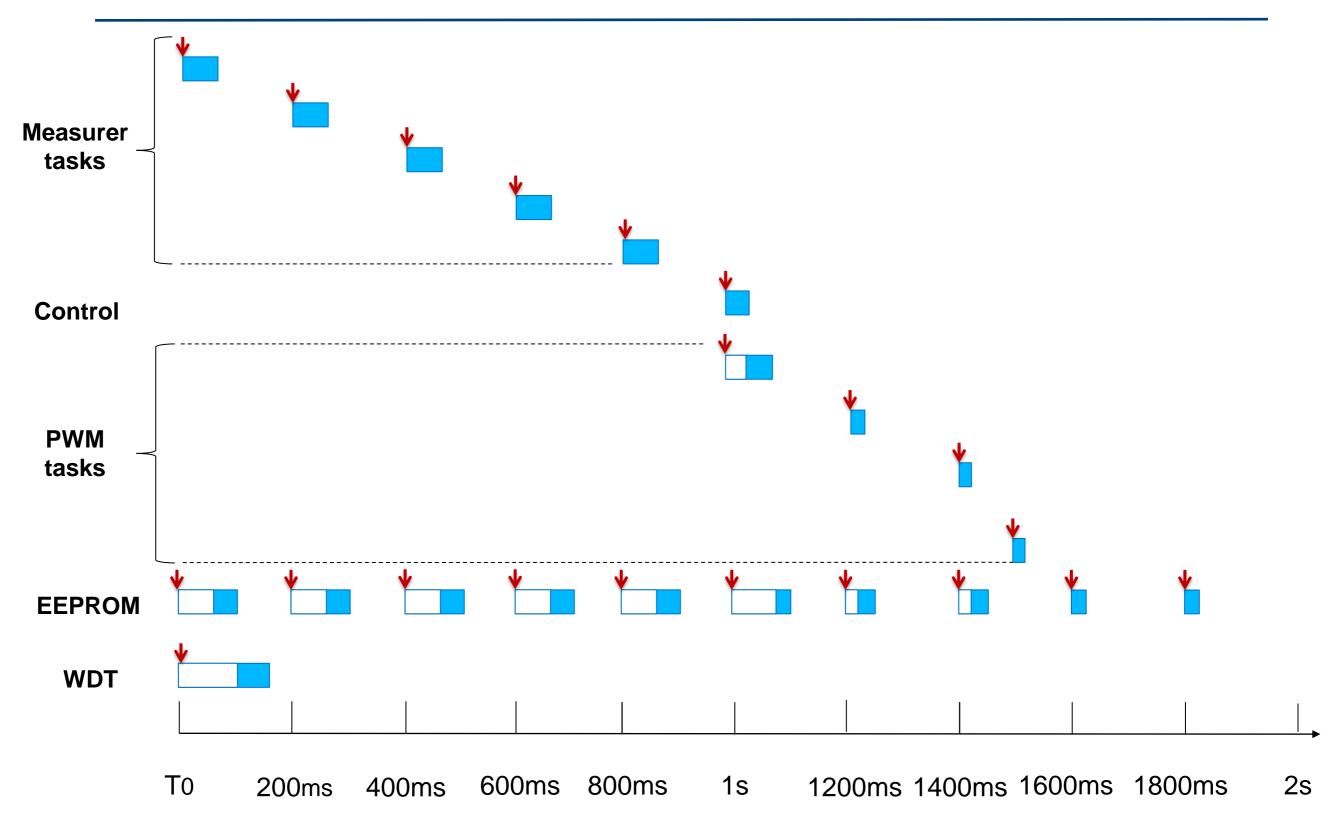
 PWM task violates the Ravenscar single activation point condition

PWM

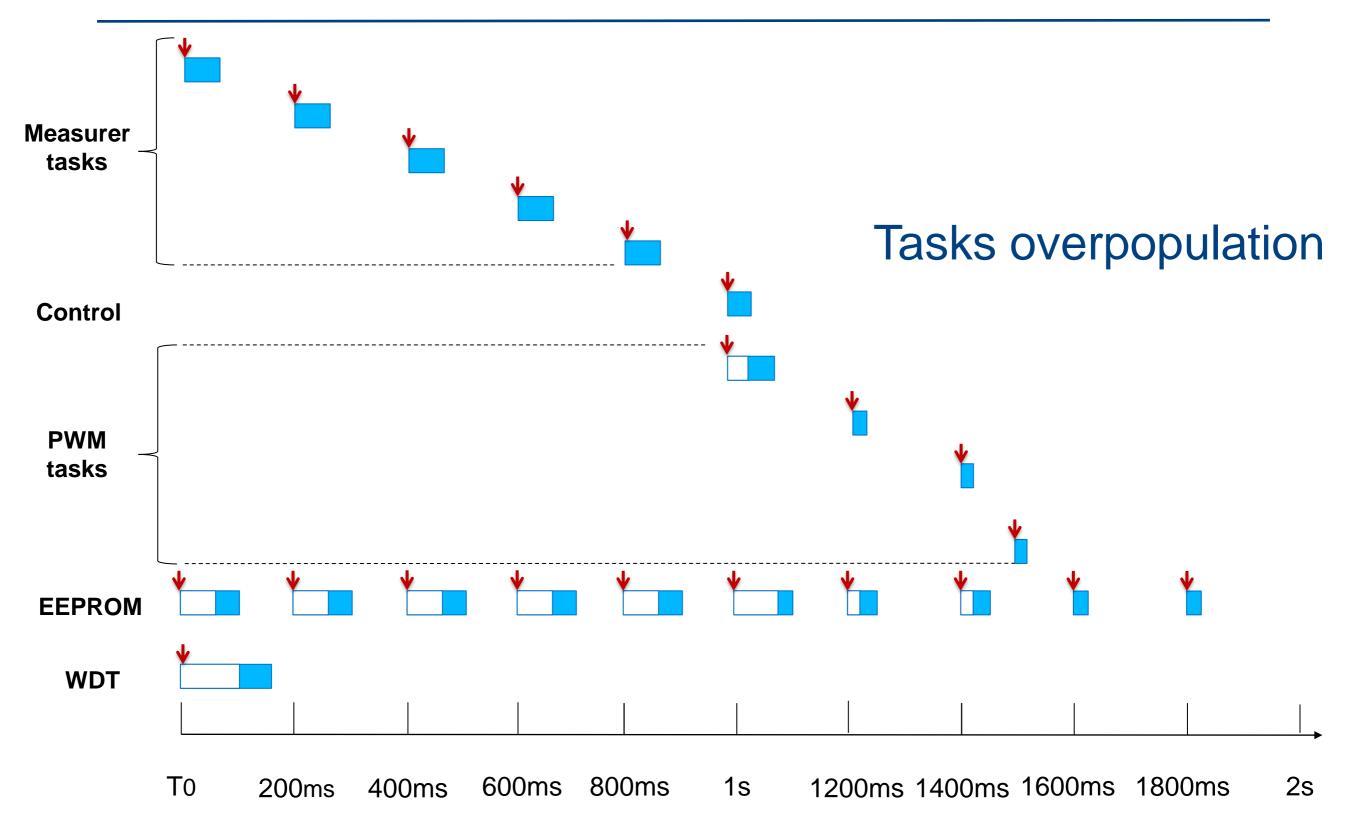
- PWM task violates the Ravenscar single activation point condition
  - It can be modeled as 4 tasks



#### Equivalent task set



#### Equivalent task set



#### Response time results

- Response time analysis using MAST
- Equivalent task set schedulable
- Processor utilization: 1.18%

Task	Period	Offset	Release jitter	Deadline	Blocking	WCET	Response
$PWM_{Off}_{-1}$	2 s	$1200~\mathrm{ms}$	$313.916~\mathrm{ms}$	800 ms	$0.048~\mathrm{ms}$	$0.8 \mathrm{ms}$	$314.584~\mathrm{ms}$
$PWM_{Off}_2$	2 s	$1200~\mathrm{ms}$	$313.916~\mathrm{ms}$	800 ms	$0.048~\mathrm{ms}$	$0.8 \mathrm{ms}$	$315.384~\mathrm{ms}$
$[PWM_{Off}_3]$	2 s	$1200~\mathrm{ms}$	$313.916~\mathrm{ms}$	800  ms	$0.048~\mathrm{ms}$	$0.8 \mathrm{ms}$	$316.184~\mathrm{ms}$
PWM <sub>On</sub>	2 s	1 s	$9.058~\mathrm{ms}$		$0.048~\mathrm{ms}$	$2.41~\mathrm{ms}$	$13.736~\mathrm{ms}$
Control	2 s	1 s	0		$0.048~\mathrm{ms}$	$4.02 \mathrm{\ ms}$	$8.878 \mathrm{\ ms}$
Measurer_1	2 s	0	0	200  ms	$0.048~\mathrm{ms}$	$2.73 \mathrm{\ ms}$	$11.608 \mathrm{\ ms}$
Measurer_2	2 s	200  ms	0	$200 \mathrm{ms}$	$0.048~\mathrm{ms}$	$2.73~\mathrm{ms}$	$14.338 \mathrm{\ ms}$
Measurer_3	2 s	400  ms	0	200 ms	$0.048~\mathrm{ms}$	$2.73~\mathrm{ms}$	$17.068 \mathrm{\ ms}$
Measurer_4	2 s	600  ms	0	200  ms	$0.048~\mathrm{ms}$	$2.73 \mathrm{\ ms}$	$19.798 \mathrm{\ ms}$
Measurer_5	2 s	800  ms	0	200 ms	$0.048~\mathrm{ms}$	$2.73 \mathrm{\ ms}$	$22.528 \mathrm{\ ms}$
EEPROM	$200 \mathrm{~ms}$	0	0	$185 \mathrm{ms}$	0	$0.87 \mathrm{\ ms}$	$22.528 \mathrm{\ ms}$
WDT	10 s	0	0	$5 \mathrm{s}$	0	$1 \mathrm{ms}$	$23.567 \mathrm{\ ms}$

#### Conclusions

- UPMSat-2 used as an experimental case study
- Validation of development approaches:
  - MultiPARTES, TASTE
  - GNAT Pro tools
  - Simulink automatic code generation
- Schedulability analysis feasible and successful using an equivalent task set

#### Future work

- Use QGen for ADCS
- Include SPARK
- Complete schedulability analysis
- Complete integration and testing

- IDR UPM coordination of UPMSat-2 project
- AdaCore supplying development and analysis tools
- Rapitime and AbsInt providing timing analysis tools
- Tecnobit and Emxys OBC and radio equipment
- Universidad de Cantabria MAST support